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ECU tune is needed to get rid of it. Great truck and I definitely don't see this being ...

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the one complaint I do have is that the speed is capped electronically at 90 mph, and from what I've found an ECU tune is needed to get rid of it. Great truck and I definitely don't see this being ...

This is an engine rebuilding and modification guide that includes sections on history, engine specs, disassembly, cylinder block and bottom end

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reconditioning, cylinder heads and valvetrain
reconditioning, balancing, step-by-step engine
reassembly, torque values, and OEM part numbers for
the popular Chevy LS series of engines.

When it comes to their personal transportation, today's youth have shunned the large, heavy performance cars of their parents' generation and instead embraced what has become known as the "sport compact"--smaller, lightweight, modern sports cars of predominantly Japanese manufacture. These cars respond well to performance modifications due to their light weight and technology-laden, high-revving engines. And by far, the most sought-after and modified cars are the Hondas

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and Acuras of the mid-'80s to the present. An extremely popular method of improving vehicle performance is a process known as engine swapping. Engine swapping consists of removing a more powerful engine from a better-equipped or more modern vehicle and installing it into your own. It is one of the most efficient and affordable methods of improving your vehicle's performance. This book covers in detail all the most popular performance swaps for Honda Civic, Accord, and Prelude as well as the Acura Integra. It includes vital information on electrics, fit, and drivetrain compatibility, design considerations, step-by-step instruction, and costs. This book is must-have for the Honda enthusiast.

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This book presents operational and practical issues of automotive mechatronics with special emphasis on the heterogeneous automotive vehicle systems approach, and is intended as a graduate text as well as a reference for scientists and engineers involved in the design of automotive mechatronic control systems. As the complexity of automotive vehicles increases, so does the dearth of high competence, multi-disciplined automotive scientists and engineers. This book provides a discussion into the type of mechatronic control systems found in modern vehicles and the skills required by automotive scientists and engineers working in this environment. Divided into two volumes

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and five parts, Automotive Mechatronics aims at improving automotive mechatronics education and emphasises the training of students ' experimental hands-on abilities, stimulating and promoting experience among high education institutes and produce more automotive mechatronics and automation engineers. The main subject that are treated are:

VOLUME I: RBW or XBW unibody or chassis-motion mechatronic control hypersystems; DBW AWD propulsion mechatronic control systems; BBW AWB dispulsion mechatronic control systems; VOLUME II: SBW AWS diversion mechatronic control systems; ABW AWA suspension mechatronic control systems. This volume was developed for undergraduate and

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postgraduate students as well as for professionals involved in all disciplines related to the design or research and development of automotive vehicle dynamics, powertrains, brakes, steering, and shock absorbers (dampers). Basic knowledge of college mathematics, college physics, and knowledge of the functionality of automotive vehicle basic propulsion, dispulsion, conversion and suspension systems is required.

This is a comprehensive collection of proven strategies and tools for effective online teaching, based on the principles of learning as a social process. It offers practical, contemporary guidance to support e-learning

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decision-making, instructional choices, as well as program and course planning, and development.

With this volume, Ezequiel P. M. Leiva and co-authors fill a gap in the available literature, by providing a much-needed, comprehensive review of the relevant literature for electrochemists, materials scientists and energy researchers. For the first time, they present applications of underpotential deposition (UPD) on the nanoscale, such as nanoparticles and nanocavities, as well as for electrocatalysis. They also discuss real surface determinations and layer-by-layer growth of ultrathin films, as well as the very latest modeling approaches to UPD based on nanothermodynamics,

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statistical mechanics, molecular dynamics and Monte-Carlo simulations.

Modern cars are more computerized than ever. Infotainment and navigation systems, Wi-Fi, automatic software updates, and other innovations aim to make driving more convenient. But vehicle technologies haven't kept pace with today's more hostile security environment, leaving millions vulnerable to attack. The Car Hacker's Handbook will give you a deeper understanding of the computer systems and embedded software in modern vehicles. It begins by examining vulnerabilities and providing detailed explanations of communications over the CAN bus and between devices

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and systems. Then, once you have an understanding of a vehicle ' s communication network, you ' ll learn how to intercept data and perform specific hacks to track vehicles, unlock doors, glitch engines, flood communication, and more. With a focus on low-cost, open source hacking tools such as Metasploit, Wireshark, Kayak, can-utils, and ChipWhisperer, The Car Hacker ' s Handbook will show you how to:

- Build an accurate threat model for your vehicle
- Reverse engineer the CAN bus to fake engine signals
- Exploit vulnerabilities in diagnostic and data-logging systems
- Hack the ECU and other firmware and embedded systems
- Feed exploits through infotainment and vehicle-to-vehicle communication systems
- Override

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factory settings with performance-tuning techniques
– Build physical and virtual test benches to try out exploits safely If you ' re curious about automotive security and have the urge to hack a two-ton computer, make The Car Hacker ' s Handbook your first stop.

This book is focused on the use of deep learning (DL) and artificial intelligence (AI) as tools to advance the fields of malware detection and analysis. The individual chapters of the book deal with a wide variety of state-of-the-art AI and DL techniques, which are applied to a number of challenging malware-related problems. DL and AI based approaches to malware detection and analysis are largely data driven and hence minimal

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expert domain knowledge of malware is needed. This book fills a gap between the emerging fields of DL/AI and malware analysis. It covers a broad range of modern and practical DL and AI techniques, including frameworks and development tools enabling the audience to innovate with cutting-edge research advancements in a multitude of malware (and closely related) use cases.

Learn how automotive Ethernet is revolutionizing in-car networking from the experts at the core of its development. Providing an in-depth account of automotive Ethernet, from its background and development, to its future prospects, this book is ideal

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for industry professionals and academics alike.

This series of comprehensive manuals gives the home mechanic an in-depth look at specific areas of auto repair.

Ever stringent vehicle safety legislation and consumer expectations inspire the improvement of vehicle dynamic performance, which result in a rising number of control strategies for vehicle dynamics that rely on driving conditions. Road profiles, as the primary excitation source of vehicle systems, play a critical role in vehicle dynamics and also in public transportation. Knowledge of precise road conditions can thus be of

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great assistance for vehicle companies and government departments to develop proper dynamic control algorithms, and to fix roads in a timely manner and at the minimum cost, respectively. As a result, developing easy-to-use and accurate road estimation methods are of great importance in terms of reducing the cost related to vehicles and road maintenance as well as improving passenger comfort and handling capacity. A few books have already been published on road profile modeling and the influence of road unevenness on vehicle response. However, there is still room to discuss road assessment methods based on vehicle response and how road conditions can be used to improve vehicle dynamics. In this book, we use several

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generalized vehicle models to demonstrate the concepts, methods, and applications of vehicle response-based road estimation algorithms. In addition, necessary tools, algorithms, and methods are illustrated, and the benefits of the road estimation algorithms are evaluated. Furthermore, several case studies of controllable suspension systems to improve vehicle vertical dynamics are presented.

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